6. Matrices

Outline

Matrices

Matrix-vector multiplication

Examples

Matrices

► a *matrix* is a rectangular array of numbers, *e.g.*,

0	1	-2.3	0.1
1.3	4	-0.1	0
4.1	-1	0	1.7

- its size is given by (row dimension) × (column dimension)
 e.g., matrix above is 3 × 4
- elements also called entries or coefficients
- B_{ij} is *i*, *j* element of matrix *B*
- ▶ *i* is the *row index*, *j* is the *column index*; indexes start at 1
- two matrices are equal (denoted with =) if they are the same size and corresponding entries are equal

Matrix shapes

an $m \times n$ matrix A is

- ► *tall* if *m* > *n*
- ▶ *wide* if *m* < *n*
- square if m = n

Column and row vectors

- we consider an $n \times 1$ matrix to be an *n*-vector
- we consider a 1×1 matrix to be a number
- a $1 \times n$ matrix is called a *row vector*, *e.g.*,

$$\begin{bmatrix} 1.2 & -0.3 & 1.4 & 2.6 \end{bmatrix}$$

which is *not* the same as the (column) vector

$$\begin{bmatrix} 1.2 \\ -0.3 \\ 1.4 \\ 2.6 \end{bmatrix}$$

Columns and rows of a matrix

- suppose A is an $m \times n$ matrix with entries A_{ij} for i = 1, ..., m, j = 1, ..., n
- ▶ its *j*th *column* is (the *m*-vector)

$$\left[egin{array}{c} A_{1j} \ dots \ A_{mj} \end{array}
ight]$$

▶ its *i*th *row* is (the *n*-row-vector)

$$\left[\begin{array}{ccc}A_{i1}&\cdots&A_{in}\end{array}\right]$$

► *slice* of matrix: $A_{p:q,r:s}$ is the $(q - p + 1) \times (s - r + 1)$ matrix

$$A_{p:q,r:s} = \begin{bmatrix} A_{pr} & A_{p,r+1} & \cdots & A_{ps} \\ A_{p+1,r} & A_{p+1,r+1} & \cdots & A_{p+1,s} \\ \vdots & \vdots & & \vdots \\ A_{qr} & A_{q,r+1} & \cdots & A_{qs} \end{bmatrix}$$

Block matrices

we can form *block matrices*, whose entries are matrices, such as

$$A = \left[\begin{array}{cc} B & C \\ D & E \end{array} \right]$$

where *B*, *C*, *D*, and *E* are matrices (called *submatrices* or *blocks* of *A*)

- matrices in each block row must have same height (row dimension)
- matrices in each block column must have same width (column dimension)
- example: if

$$B = \begin{bmatrix} 0 & 2 & 3 \end{bmatrix}, \quad C = \begin{bmatrix} -1 \end{bmatrix}, \quad D = \begin{bmatrix} 2 & 2 & 1 \\ 1 & 3 & 5 \end{bmatrix}, \quad E = \begin{bmatrix} 4 \\ 4 \end{bmatrix}$$

then

$$\begin{bmatrix} B & C \\ D & E \end{bmatrix} = \begin{bmatrix} 0 & 2 & 3 & -1 \\ 2 & 2 & 1 & 4 \\ 1 & 3 & 5 & 4 \end{bmatrix}$$

Column and row representation of matrix

• A is an $m \times n$ matrix

• can express as block matrix with its (*m*-vector) columns a_1, \ldots, a_n

$$A = \begin{bmatrix} a_1 & a_2 & \cdots & a_n \end{bmatrix}$$

• or as block matrix with its (*n*-row-vector) rows b_1, \ldots, b_m

$$A = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{bmatrix}$$

Examples

- *image:* X_{ij} is *i*,*j* pixel value in a monochrome image
- rainfall data: A_{ij} is rainfall at location *i* on day *j*
- multiple asset returns: R_{ij} is return of asset j in period i
- contingency table: A_{ij} is number of objects with first attribute *i* and second attribute *j*
- *feature matrix:* X_{ij} is value of feature *i* for entity *j*

in each of these, what do the rows and columns mean?

Graph or relation

• a *relation* is a set of pairs of *objects*, labeled $1, \ldots, n$, such as

 $\mathcal{R} = \{(1,2), (1,3), (2,1), (2,4), (3,4), (4,1)\}$

same as directed graph



► can be represented as $n \times n$ matrix with $A_{ij} = 1$ if $(i,j) \in \mathcal{R}$

$$A = \begin{bmatrix} 0 & 1 & 1 & 0 \\ 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \end{bmatrix}$$

Special matrices

- $m \times n$ zero matrix has all entries zero, written as $0_{m \times n}$ or just 0
- *identity matrix* is square matrix with $I_{ii} = 1$ and $I_{ij} = 0$ for $i \neq j$, *e.g.*,

$$\left[\begin{array}{rrrr}1&0\\0&1\end{array}\right],\qquad \left[\begin{array}{rrrr}1&0&0&0\\0&1&0&0\\0&0&1&0\\0&0&0&1\end{array}\right]$$

- sparse matrix: most entries are zero
 - examples: 0 and I
 - can be stored and manipulated efficiently
 - $\mathbf{nnz}(A)$ is number of nonzero entries

Diagonal and triangular matrices

- *diagonal matrix*: square matrix with $A_{ij} = 0$ when $i \neq j$
- **diag** (a_1, \ldots, a_n) denotes the diagonal matrix with $A_{ii} = a_i$ for $i = 1, \ldots, n$
- example:

$$\mathbf{diag}(0.2, -3, 1.2) = \begin{bmatrix} 0.2 & 0 & 0\\ 0 & -3 & 0\\ 0 & 0 & 1.2 \end{bmatrix}$$

- *lower triangular matrix*: $A_{ij} = 0$ for i < j
- upper triangular matrix: $A_{ij} = 0$ for i > j
- examples:

$$\begin{bmatrix} 1 & -1 & 0.7 \\ 0 & 1.2 & -1.1 \\ 0 & 0 & 3.2 \end{bmatrix}$$
 (upper triangular),
$$\begin{bmatrix} -0.6 & 0 \\ -0.3 & 3.5 \end{bmatrix}$$
 (lower triangular)

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Transpose

• the *transpose* of an $m \times n$ matrix A is denoted A^T , and defined by

$$(A^T)_{ij} = A_{ji}, \quad i = 1, ..., n, \quad j = 1, ..., m$$

► for example,

0	4 -			-	•	Ъ
7	0	=	0	1	3	
3	1		. 4	0	1]

transpose converts column to row vectors (and vice versa)

 $\blacktriangleright (A^T)^T = A$

Addition, subtraction, and scalar multiplication

(just like vectors) we can add or subtract matrices of the same size:

$$(A + B)_{ij} = A_{ij} + B_{ij}, \quad i = 1, \dots, m, \quad j = 1, \dots, n$$

(subtraction is similar)

scalar multiplication:

$$(\alpha A)_{ij} = \alpha A_{ij}, \quad i = 1, \dots, m, \quad j = 1, \dots, n$$

many obvious properties, e.g.,

A + B = B + A, $\alpha(A + B) = \alpha A + \alpha B$, $(A + B)^T = A^T + B^T$

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Matrix norm

• for $m \times n$ matrix A, we define

$$|A|| = \left(\sum_{i=1}^{m} \sum_{j=1}^{n} A_{ij}^{2}\right)^{1/2}$$

- agrees with vector norm when n = 1
- satisfies norm properties:

 $\|\alpha A\| = |\alpha| \|A\|$ $\|A + B\| \le \|A\| + \|B\|$ $\|A\| \ge 0$ $\|A\| = 0$ only if A = 0

- distance between two matrices: ||A B||
- (there are other matrix norms, which we won't use)

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Matrix-vector product

• *matrix-vector product* of $m \times n$ matrix A, n-vector x, denoted y = Ax, with

$$y_i = A_{i1}x_1 + \dots + A_{in}x_n, \quad i = 1, \dots, m$$

► for example,

$$\begin{bmatrix} 0 & 2 & -1 \\ -2 & 1 & 1 \end{bmatrix} \begin{bmatrix} 2 \\ 1 \\ -1 \end{bmatrix} = \begin{bmatrix} 3 \\ -4 \end{bmatrix}$$

Row interpretation

• y = Ax can be expressed as

$$y_i = b_i^T x, \quad i = 1, \dots, m$$

where b_1^T, \ldots, b_m^T are rows of A

- so y = Ax is a 'batch' inner product of all rows of A with x
- example: A1 is vector of row sums of matrix A

Column interpretation

• y = Ax can be expressed as

$$y = x_1a_1 + x_2a_2 + \cdots + x_na_n$$

where a_1, \ldots, a_n are columns of A

- so y = Ax is linear combination of columns of A, with coefficients x_1, \ldots, x_n
- important example: $Ae_j = a_j$
- columns of A are linearly independent if Ax = 0 implies x = 0

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General examples

- 0x = 0, *i.e.*, multiplying by zero matrix gives zero
- Ix = x, *i.e.*, multiplying by identity matrix does nothing
- inner product $a^T b$ is matrix-vector product of $1 \times n$ matrix a^T and *n*-vector *b*
- $\tilde{x} = Ax$ is de-meaned version of x, with

$$A = \begin{bmatrix} 1 - 1/n & -1/n & \cdots & -1/n \\ -1/n & 1 - 1/n & \cdots & -1/n \\ \vdots & & \ddots & \vdots \\ -1/n & -1/n & \cdots & 1 - 1/n \end{bmatrix}$$

Difference matrix

• $(n-1) \times n$ difference matrix is

$$D = \begin{bmatrix} -1 & 1 & 0 & \cdots & 0 & 0 & 0 \\ 0 & -1 & 1 & \cdots & 0 & 0 & 0 \\ & \ddots & \ddots & & & \\ 0 & 0 & 0 & \cdots & -1 & 1 & 0 \\ 0 & 0 & 0 & \cdots & 0 & -1 & 1 \end{bmatrix}$$

y = Dx is (n - 1)-vector of differences of consecutive entries of *x*:

$$Dx = \begin{bmatrix} x_2 - x_1 \\ x_3 - x_2 \\ \vdots \\ x_n - x_{n-1} \end{bmatrix}$$

• *Dirichlet energy:* $||Dx||^2$ is measure of wiggliness for x a time series

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Return matrix – portfolio vector

- *R* is $T \times n$ matrix of asset returns
- R_{ij} is return of asset j in period i (say, in percentage)
- *n*-vector *w* gives portfolio (investments in the assets)
- *T*-vector Rw is time series of the portfolio return
- avg(Rw) is the portfolio (mean) return, std(Rw) is its risk

Feature matrix – weight vector

- $X = [x_1 \cdots x_N]$ is $n \times N$ feature matrix
- column x_j is feature *n*-vector for object or example *j*
- X_{ij} is value of feature *i* for example *j*
- *n*-vector *w* is weight vector
- $s = X^T w$ is vector of scores for each example; $s_j = x_j^T w$

Input – output matrix

- A is $m \times n$ matrix
- y = Ax
- *n*-vector x is *input* or *action*
- *m*-vector *y* is *output* or *result*
- A_{ij} is the factor by which y_i depends on x_j
- A_{ij} is the *gain* from input *j* to output *i*
- *e.g.*, if A is lower triangular, then y_i only depends on x_1, \ldots, x_i